

Periodicity and large time behavior for excitable mean-field systems.

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Joint works with Christophe Poquet (Lyon 1).

Outline

- 1 Mean-field excitable systems
- 2 Emergence of periodicity when $N = \infty$
- 3 The case $N < \infty$: the empirical measure on long time scales

A general model of mean-field particles

Consider N interacting diffusions $X_t^i \in \mathbb{R}^d$, $i = 1, \dots, N$, $t \geq 0$ solving

$$dX_t^i = \left(\delta F(X_t^i) - K \left(X_t^i - \frac{1}{N} \sum_{j=1}^N X_t^j \right) \right) dt + \sqrt{2} \sigma dB_t^i$$

The above dynamics is decomposed into :

- **Local dynamics** : $\delta F(X_t^i)dt$, ($\delta > 0$: scaling parameter),
- **Linear interaction with the mean value** : $-K \left(X_t^i - \frac{1}{N} \sum_{j=1}^N X_t^j \right)$,
($K = \text{diag}(k_1, \dots, k_d)$, $k_i > 0$: matrix of interaction),
- **Noise** : B^1, \dots, B^N : standard i.i.d. Brownian motions,
($\sigma = \text{diag}(\sigma_1, \dots, \sigma_d)$, $\sigma_i > 0$: diffusion coefficients).

Motivation : excitable systems

The local dynamics of each particle is governed by

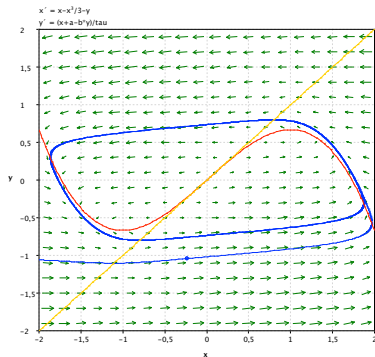
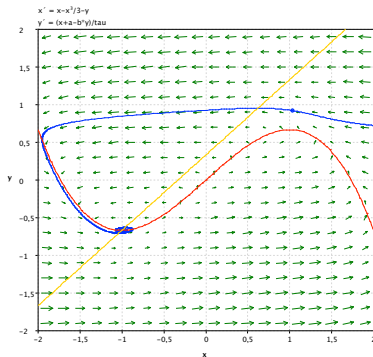
$$dX_t = F(X_t)dt$$

Excitable system [\[Lindner 2004\]](#) :

- without perturbation : rests in a stable state,
- with a sufficiently strong perturbation : the system leaves this resting state, resulting in a large excursion in the phase space.

An example : FitzHugh-Nagumo model : $X_t = (v_t, w_t) \in \mathbb{R}^2$, (v_t : membrane potential) and

$$F(X) = F(v, w) = \left(v - \frac{v^3}{3} - w, \frac{1}{c}(v + a - bw) \right), \quad a, b, c \in \mathbb{R}.$$



One is particularly interested in phenomena like

- **Persistence of oscillatory behaviors** (e.g. when individual oscillations persist for the whole macroscopic population)
- **Emergence of macroscopic structured dynamics** due to **noise** and **interaction** (when individual dynamics is not oscillatory)

Kinetic or not kinetic

Two frameworks for FHN :

- The case with full coupling and noise :

$$\begin{cases} dV_t^i = \left(\delta \left(V_t^i - \frac{(V_t^i)^3}{3} - W_t^i \right) - k_1 \left(V_t^i - \frac{1}{N} \sum_{j=1}^N V_t^j \right) \right) dt + \sqrt{2}\sigma_1 dB_t^{i,V}, \\ dW_t^i = \left(\frac{\delta}{c} (V_t^i + a - bW_t^i) - k_2 \left(W_t^i - \frac{1}{N} \sum_{j=1}^N W_t^j \right) \right) dt + \sqrt{2}\sigma_2 dB_t^{i,W} \end{cases}$$

- The kinetic case : interaction and noise only on the V variable :

$$\begin{cases} dV_t^i = \left(\delta \left(V_t^i - \frac{(V_t^i)^3}{3} - W_t^i \right) - k_1 \left(V_t^i - \frac{1}{N} \sum_{j=1}^N V_t^j \right) \right) dt + \sqrt{2}\sigma_1 dB_t^{i,V}, \\ dW_t^i = \frac{\delta}{c} (V_t^i + a - bW_t^i) dt \end{cases}$$

Emergence of periodicity : 1) not enough noise

Emergence of periodicity : 2) some more noise

Behavior of the system as $N \rightarrow \infty$ on $[0, T]$

$$dX_{i,t} = \left(\delta F(X_{i,t}) - K \left(X_{i,t} - \frac{1}{N} \sum_{j=1}^N X_{j,t} \right) \right) dt + \sqrt{2}\sigma dB_{i,t}$$

Let μ_N be the empirical measure

$$\mu_{N,t} = \frac{1}{N} \sum_{j=1}^N \delta_{X_{j,t}}.$$

Then, under mild assumptions on F , [Sznitman, McKean] $\mu_{N,t} \xrightarrow[N \rightarrow \infty]{} \mu_t$
weak solution to the nonlinear Fokker-Planck (NFP) equation

$$\partial_t \mu_t = -\delta \nabla \cdot (F(x) \mu_t) + \nabla \cdot \left(K \left(x - \int y \mu_t(dy) \right) \right) + \nabla \cdot (\sigma^2 \nabla \mu_t).$$

More precisely, take e.g. the bounded-Lipschitz distance

$$d_{BL}(\mu, \nu) := \sup_{\|f\|_{Lip} \leq 1} \left| \int f d\mu - \int f d\nu \right|,$$

$$\mathbf{E} \left[\sup_{0 \leq t \leq T} d_{BL}(\mu_{N,t}, \mu_t) \right] \leq \frac{e^{CT}}{\sqrt{N}}.$$

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- 1 Mean-field excitable systems
- 2 Emergence of periodicity when $N = \infty$**
- 3 The case $N < \infty$: the empirical measure on long time scales

Question 1 : emergence of periodic solutions for the NFP

$$\partial_t \mu_t = -\delta \nabla \cdot (F(x) \mu_t) + \nabla \cdot \left(K \left(x - \int y \mu_t(dy) \right) \right) + \nabla \cdot (\sigma^2 \nabla \mu_t).$$

μ is the law of the nonlinear process

$$dX_t = \delta F(x_t) dt - K(X_t - \mathbf{E}[X_t]) dt + dB_t$$

Previous works

- [Mischler, Quiñinao, Touboul 2016] : long-time analysis for the FHN model in the kinetic case, in the regime $k_1 \rightarrow 0$.
- [Quiñinao, Touboul 2018] : long-time analysis for the kinetic FHN model when $\sigma \rightarrow 0$.

Here, we are looking at the regime of strong noise and interaction w.r.t. the individual dynamics, namely

K and σ are fixed and $\delta \ll 1$.

Taking $\delta \rightarrow 0$: a slow-fast analysis

$$\partial_t \mu_t = \nabla \cdot (\sigma^2 \nabla \mu_t) + \nabla \cdot \left(K \mu_t(x) \left(x - \int_{\mathbb{R}^d} z \mu_t(dz) \right) - \delta \nabla \cdot (\mu_t(x) F(x)) \right).$$

The main point of the analysis is to decompose the process μ_t in terms of

- its mean value $m_t = \int_{\mathbb{R}^d} z \mu_t(dz)$
- the centered process p_t defined by

$$\int_{\mathbb{R}^d} \varphi(x) p_t(dx) := \int_{\mathbb{R}^d} \varphi(x - m_t) \mu_t(dx).$$

Rewriting everything in terms of (p_t, m_t) , we obtain

$$\begin{cases} \partial_t p_t(x) &= \nabla \cdot (\sigma^2 \nabla p_t(x)) + \nabla \cdot (p_t(x) (Kx + \dot{m}_t - \delta F(x + m_t))) \\ \dot{m}_t &= \delta \int_{\mathbb{R}^d} F(x + m_t) p_t(dx) \end{cases}$$

This is a slow-fast dynamics !

The case $\delta = 0$: a simple Ornstein-Uhlenbeck process

In the case $\delta = 0$, the non-linear process reads

$$d\bar{X}_t = -K (\bar{X}_t - \mathbb{E}(\bar{X}_t)) dt + \sqrt{2}\sigma dB_t.$$

Hence, the mean-value $\mathbb{E}(\bar{X}_t) = m_0$ is constant and the dynamics of the process μ_t is simply given by

$$\partial_t \mu_t = \nabla \cdot (\sigma^2 \nabla \mu_t(x)) + \nabla \cdot (\mu_t(x) K x).$$

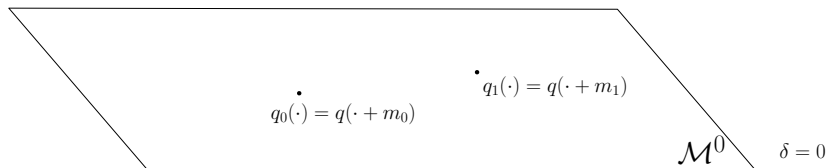
This is nothing else than the law of the Ornstein-Uhlenbeck process !
In this case, the dynamics is reversible and we have exponential convergence to a Gaussian invariant measure :

$$\|\mu_t - q\|_{L^2(w)} \leq e^{-k_0 t} \|\mu_0 - q\|_{L^2(w)},$$

for

$$q(x) = \frac{1}{((2\pi)^d \det(\sigma^2 K^{-1}))^{\frac{1}{2}}} \exp\left(-\frac{1}{2} x \cdot K \sigma^{-2} x\right), \quad x \in \mathbb{R}^d.$$

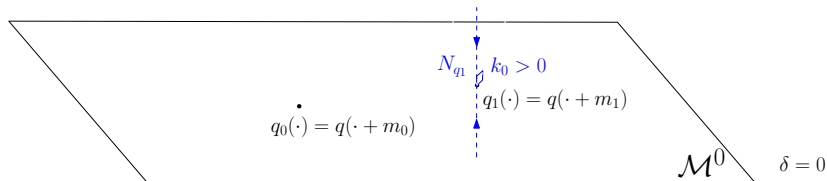
Perturbing normally hyperbolic invariant manifolds



Claim

- For $\delta = 0$, there is a trivial normally hyperbolic invariant (Gaussian) manifold for the evolution.
- Such structure is stable by small perturbations (Geometric singular perturbation theory : [\[Fenichel 1972\]](#), [\[Giacomin, Pakdaman, Pellegrin, Poquet 2012\]](#), [\[Wiggins 2013\]](#))

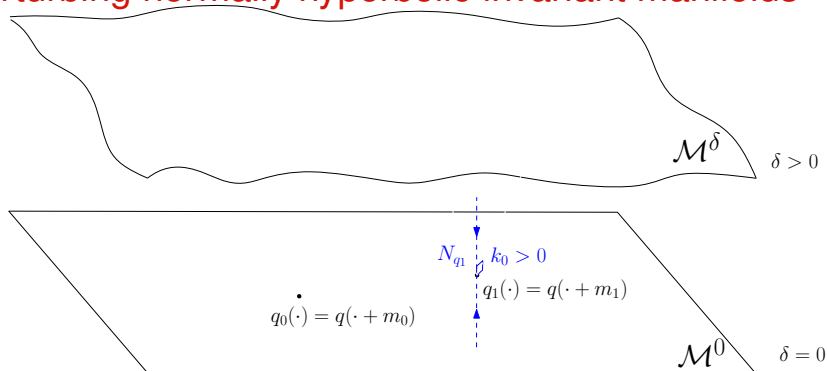
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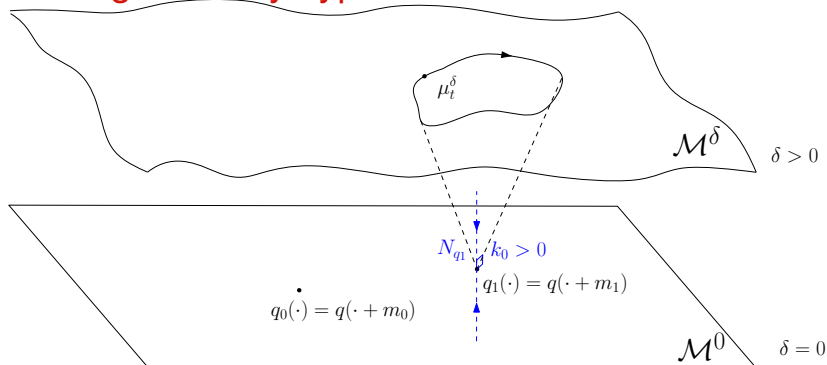
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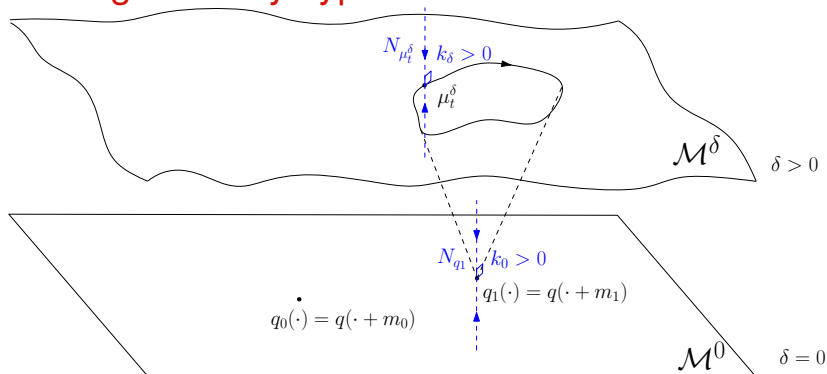
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What is, at first order in δ , the dynamics of the mean-value m along the perturbed manifold ?

$$\begin{cases} \partial_t p_t(x) &= \nabla \cdot (\sigma^2 \nabla p_t(x)) + \nabla \cdot (p_t(x)(Kx + \dot{m}_t - \delta F(x + m_t))) \\ \dot{m}_t &= \delta \int_{\mathbb{R}^d} F(x + m_t) p_t(dx) \end{cases}$$

Intuitively,

- The fast component $\mu_t^\delta \approx \mu_t^{\delta=0}$ which converges exponentially fast to its invariant measure q .
- Hence, it is natural to replace μ_t^δ by the Gaussian measure q in the slow component m .
- Thus, it is natural to expect

$$\dot{m}_t = \delta \int_{\mathbb{R}^d} F(x + m_t) q(x) dx + O(\delta^2).$$

Theorem (L., Poquet, 2019)

There exists $\bar{\delta} > 0$ such that for all $0 \leq \delta \leq \bar{\delta}$, there exists a positively invariant manifold $\mathcal{M}^\delta = \{(p_m^\delta, m)\}_m$ for the nonlinear Fokker-Planck PDE, where μ_m^δ is a probability measure on \mathbb{R}^d .

- \mathcal{M}^δ is a perturbation of size δ of the Gaussian manifold \mathcal{M}^0

$$\sup_m \|p_m^\delta - q\|_{L^2(w)} \leq C\delta.$$

- \mathcal{M}^δ is stable in the following sense : if $\|p_0 - p_{m_0}^\delta\|_{L^2(w)} \leq c\delta$, then

$$\|p_t - p_{m_t}^\delta\|_{L^2(w')} \leq ce^{-\lambda t} \|p_0 - p_{m_0}^\delta\|_{L^2(w')}$$

- The trajectory $t \mapsto m_t^\delta$ of the mean-value of $\mu_{m_t}^\delta$ has the following expansion :

$$\dot{m}_t^\delta = \delta \int_{\mathbb{R}^d} F(u + m_t) q(u) du + \delta^2 g^\delta(m_t^\delta),$$

with $\|g^\delta\| \leq C$.

Idea of proof : balance between dynamics and equilibrium

Define the Ornstein-Uhlenbeck operator

$$\mathcal{L}f = \nabla \cdot (\sigma^2 \nabla f) + \nabla \cdot (Kx f).$$

Then,

$$\partial_t(p_t - q_0) = \mathcal{L}(p_t - q_0) + \nabla \cdot (p_t \dot{m}_t) - \delta \nabla \cdot (p_t F_t).$$

The key estimate is

$$\frac{1}{2} \frac{d}{dt} \|p_t - q_0\|_{L^2(w)}^2 \leq -(k - c'\delta) \|p_t - q_0\|_{L^2(w)}^2 + C\delta \|p_t - q_0\|_{L^2(w)},$$

which gives

$$\|p_t - q_0\|_{L^2(w)} \leq \max(\|p_0 - q_0\|_{L^2(w)}, C\delta)$$

To sum up

With this result, the dynamics of the infinite dimensional measure μ_t along the manifold \mathcal{M}^δ can be parameterized by the finite dimensional dynamics of its mean-value m_t^δ .

Namely, everything boils down to comparing now

- the dynamics of an isolated unit

$$\dot{m}_t = F(m_t) \quad (1)$$

- with the dynamics of the mean-value of connected units, approximated at first order in δ by

$$\dot{m}_t = \delta \int_{\mathbb{R}^d} F(x + m_t) q(x) dx. \quad (2)$$

Claim

In the FHN case, for a suitable choice of parameters, Eq. (1) is in a resting state, whereas Eq. (2) oscillates : there is emergence of structured dynamics due to noise and interaction.

The FitzHugh-Nagumo model

In the case of a FHN dynamics

$$F(v, w) = \left(\textcolor{red}{v} - \frac{v^3}{3} - w, \frac{1}{c}(v + a - bw) \right),$$

with diagonal interaction $K = \begin{pmatrix} K_1 & 0 \\ 0 & K_2 \end{pmatrix}$ and noise $\sigma = \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{pmatrix}$.
Averaging F by the Gaussian kernel q gives

$$\int_{\mathbb{R}^2} F(z + (v, w)) q(z) dz = \left(\left(1 - \frac{\sigma_1^2}{K_1} \right) v - \frac{v^3}{3} - w, \frac{1}{c}(v + a - bw) \right)$$

which is again a FitzHugh Nagumo system, where the parameter $\textcolor{red}{u} = 1$ has been changed into $\textcolor{blue}{u} = 1 - \frac{\sigma_1^2}{K_1}$.

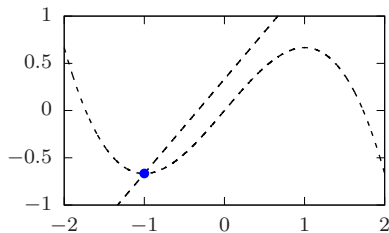
Summary

Adding noise and interaction simply means here decreasing the parameter u from 1 to $u = 1 - \frac{\sigma_1^2}{K_1} < 1$.

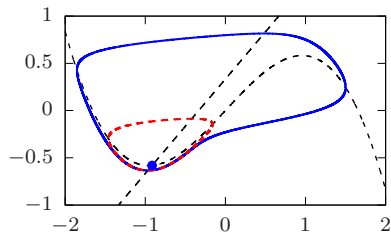
Phase transition as $u = 1 - \frac{\sigma_1^2}{K_1} \searrow 0$ for

$$\dot{v} = uv - \frac{v^3}{3} - w, \dot{w} = \frac{1}{c}(v + a - bw)$$

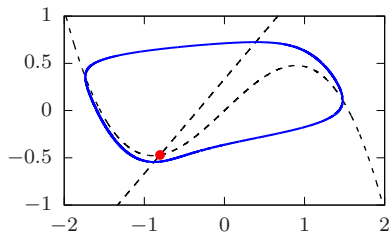
(a) $u = 1$



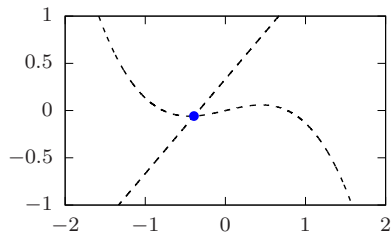
(b) $u = 0.914$



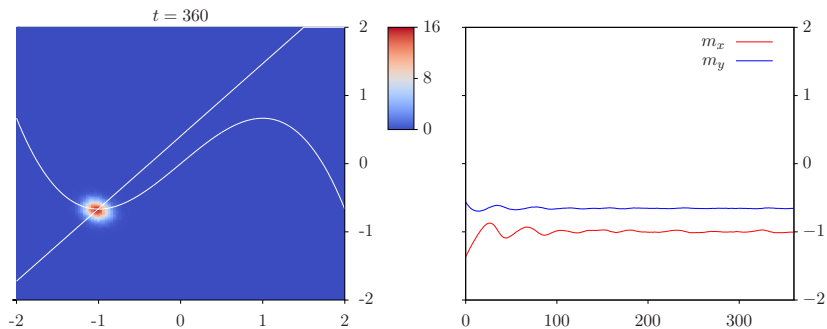
(c) $u = 0.8$



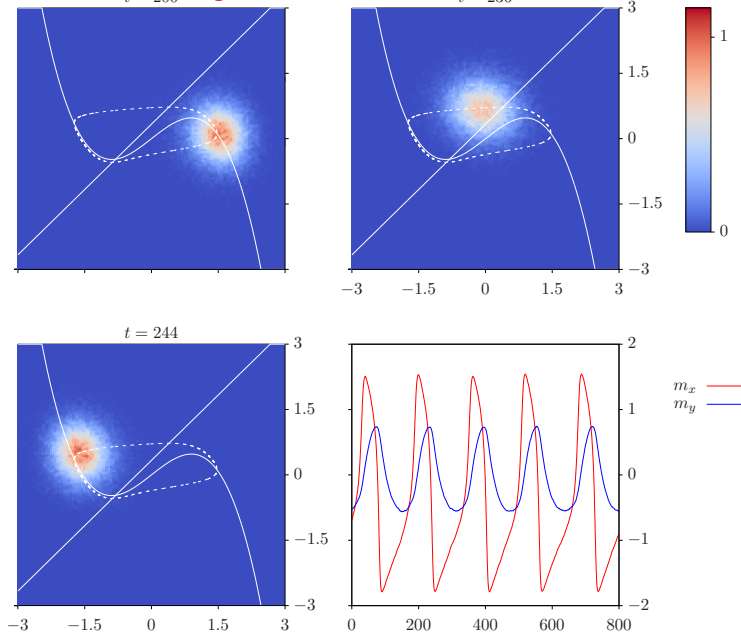
(d) $u = 0.2$



No noise : $\frac{\sigma_1^2}{K_1} = 0$ ($u = 1$)



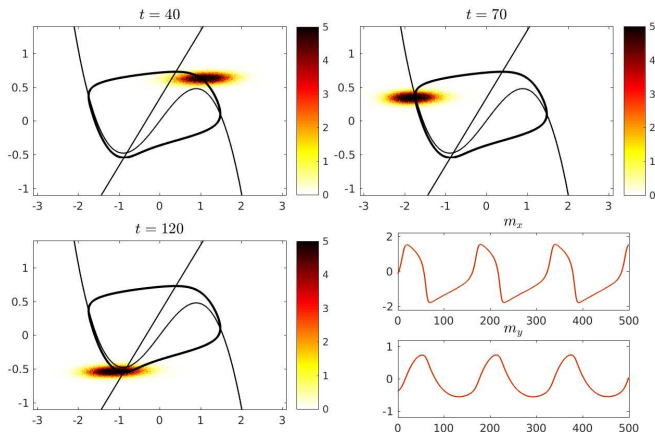
Large noise : $\frac{\sigma_1^2}{K_1} = 0.2$ ($u = 0.8$) : limit cycle



The kinetic case

[L., Poquet 2020]

$$\begin{cases} dV_{i,t} = \delta \left(V_{i,t} - \frac{V_{i,t}^3}{3} - w_{i,t} \right) dt - K_1 \left(V_{i,t} - \frac{1}{n} \sum_{j=1}^n V_{j,t} \right) dt + \sqrt{2}\sigma_1 dB_{i,t}^{(1)} \\ dw_{i,t} = \frac{\delta}{c} (V_{i,t} + a - bw_{i,t}) dt \end{cases}$$



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Question 2 : the empirical measure on large time scales

$$\mathbf{E} \left[\sup_{0 \leq t \leq T} d_{BL}(\mu_{N,t}, \mu_t) \right] \leq \frac{e^{CT}}{\sqrt{N}}.$$

The previous estimate is only relevant for bounded time intervals $T = O(1)$ (or $T \sim c \log(N)$, c small). The question we ask is the following :

- 1 Can we transpose the existence of a limit cycle for μ_t to a similar periodic behavior for the empirical measure $\mu_{N,t}$?

The answer is NO : $\mu_{N,t}$ is Markovian and for well-confining dynamics F , μ_N has a unique invariant measure. On long time-scales, the system diffuses and cannot have a periodic behavior. So it should be better to rephrase the question into

- 1 Is there a time scale α_N on which the behavior of $\mu_{N,\alpha_N t}$ remains close to the periodic solution of μ_t ?

This issue has a long story, especially in the **reversible** case where $F = -\nabla V$ for some sufficiently convex potential V ([Bolley, Guillin, Malrieu]).

A “simpler model” : phase oscillators

Here the state space is the circle \mathbb{S}^1 and $X_{i,t}$ solves

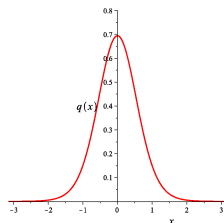
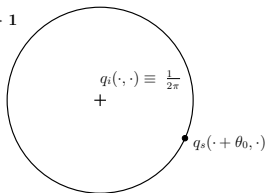
$$dX_{i,t} = \frac{K}{N} \sum_{j=1}^N \sin(X_{j,t} - X_{i,t}) dt + \sqrt{2}\sigma dB_i(t), \quad i = 1, \dots, N,$$

and the nonlinear Fokker-Planck equation reduces to

$$\partial_t \mu_t(x) = \sigma^2 \partial_x^2 \mu_t(x) - K \partial_x \left[\mu_t(x) \left(\sin * \mu_t(x) \right) \right].$$

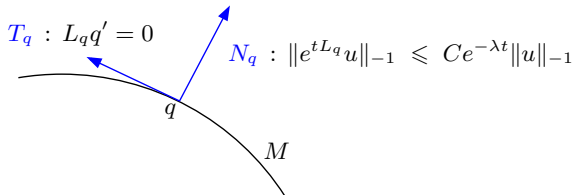
The steady states are given as a manifold of stationary steady states M

$K > 1$



Local stability of the invariant manifold

Let $L_q h := \frac{1}{2} \partial_x^2 h + K \partial_x (h \sin * q + q \sin * h)$ be the linearization around some stationary solution $q \in M$. L_q can be decomposed in $H_{1/q}^{-1}$ as follows :



This decomposition implies the local stability of M . [Dahms 2002, Bertini, Giacomini, Pakdaman, 2010], but we also have global stability [Giacomini, Pakdaman, Pellegrin, Poquet, 2012].

Long-time diffusion for the Kuramoto model :

Theorem ([Bertini, Giacomin, Poquet, 2014])

For $T > 0$ and $\varepsilon > 0$, if

$$\lim_{N \rightarrow \infty} \mathbb{P}(\mathrm{d}(\mu_{N,0}, M) \leq \varepsilon) = 1$$

then

$$\lim_{N \rightarrow \infty} \mathbb{P} \left(\sup_{t \in [\log(N)/N, T]} \|\mu_{N,tN} - q_{\psi_0 + DW_{N,t}}\|_{-1} \leq \varepsilon \right) = 1$$

where $W_{N,t}$ converges weakly to a standard Brownian motion as $N \rightarrow \infty$.

Further references

- [Brassesco, De Masi, Presutti 1998, Funaki 1995] : Allen-Cahn model.
- [L., Poquet, 2017] : extension to the case of the Kuramoto model with inhomogeneities.
- [Coppini, 2019] : long time stability results for the Kuramoto model on Erdős-Renyi graphs.
- [Giacomin, Poquet, Shapira, 2018] : long-time diffusion for SDEs with small noise in finite dimension : specific use of the isochron map to derive the motion along the limit cycle.

Going back to limit cycles in \mathbb{R}^d

Main issues concerning the previous results :

- 1 The existence of limit cycle is stated in weighted L^2 norm, too strong to accommodate for empirical measures
- 2 The existence result is not sufficiently complemented with regularity results (in particular, regularity of the isochron, a C^2 -regularity being required, as we will need to apply Ito formula)

Solutions :

- 1 We now work weighted Sobolev spaces H_θ^{-r} (recall that $\mu^n \in H_\theta^{-r}$ for $r > d/2$), for the H^{-r} space weighted by

$$w_\theta(x) = \exp\left(-\frac{\theta}{2} |x|_{K\sigma^{-2}}^2\right).$$

- 2 **Main assumption** : F and all its derivatives regular and bounded.

We use here an abstract result of [\[Bate, Lu, Zeng 2008\]](#) concerning Approximately Invariant Manifolds.

Regularity of limit cycles for the F-P equation

Recall that

$$\begin{cases} \partial_t p_t(x) &= \nabla \cdot (\sigma^2 \nabla p_t(x)) + \nabla \cdot (p_t(x)(Kx + \dot{m}_t - \delta F(x + m_t))) \\ \dot{m}_t &= \delta \int_{\mathbb{R}^d} F(x + m_t) p_t(dx) \end{cases} \quad (\text{NFP})$$

Theorem ([L., Poquet, 2021])

For some small $\delta > 0$ and large $r \geq 1$, for all $\theta \in (0, 1]$, (NFP) admits a periodic solution $(\Gamma_t^\delta)_t := (q_t^\delta, \gamma_t^\delta)_t$ in \mathbf{H}_θ^{-r} with period $T_\delta > 0$.

Moreover q_t^δ is a probability distribution for all $t \geq 0$, and $t \mapsto \partial_t \Gamma_t^\delta$ and $t \mapsto \partial_t^2 \Gamma_t^\delta$ are in $C([0, T_\delta), \mathbf{H}_\theta^{-r})$.

Secondly, there exists a neighborhood $\mathcal{W}^\delta \in \mathbf{H}_\theta^{-r}$ of Γ^δ and a C^2 mapping $\Theta^\delta : \mathcal{W}^\delta \rightarrow \mathbb{R}/T_\delta \mathbb{Z}$ that satisfies, for all $\mu \in \mathcal{W}^\delta$, denoting $\mu_t = T^t \mu$,

$$\Theta^\delta(\mu_t) = \Theta^\delta(\mu) + t \mod T_\delta,$$

and for $C_{\Theta, \delta} > 0$, for all $\mu \in \mathcal{W}^\delta$ with $\mu_t = T^t \mu$,

$$\left\| \mu_t - \Gamma_{\Theta^\delta(\mu) + t}^\delta \right\|_{\mathbf{H}_\theta^{-r}} \leq C_{\Theta, \delta} e^{-\lambda_\delta t} \left\| \mu - \Gamma_{\Theta^\delta(\mu)}^\delta \right\|_{\mathbf{H}_\theta^{-r}}.$$

Now turn to the dynamics of the empirical measure

- F-P equation :

$$\partial_t \mu_t = -\delta \nabla \cdot (F(x) \mu_t) + \nabla \cdot \left(K \left(x - \int y \mu_t(dy) \right) \mu_t \right) + \nabla \cdot (\sigma^2 \nabla \mu_t)$$

$\mu_t \leftrightarrow (p_t, m_t)$ where $\dot{m}_t := \delta \int F_{m_t} dp_t$ and

$$\partial_t p_t = \nabla \cdot (\sigma^2 \nabla p_t) + \nabla(p_t K x) - \delta \nabla \cdot \left(p_t \left(F_{m_t} - \int F_{m_t} dp_t \right) \right)$$

- Particle system :

$$dX_{i,t} = \left(\delta F(X_{i,t}) - K \left(X_{i,t} - \frac{1}{N} \sum_{j=1}^N X_{j,t} \right) \right) dt + \sqrt{2}\sigma dB_{i,t}.$$

$\mu_{N,t} \leftrightarrow (p_{N,t}, m_{N,t})$ where $m_{N,t} := \frac{1}{N} \sum_{j=1}^N X_{j,t}$ and

$$p_{N,t} := \frac{1}{N} \sum_{j=1}^N \delta_{X_{j,t} - m_{N,t}}.$$

The main result for the particle system

Theorem ([L., Poquet, 2021])

Under the previous hypotheses, if

$$\mathbb{P} \left(\|\mu_{N,0} - \Gamma_{u_0}\|_{-r} \leq \varepsilon \right) \xrightarrow{N \rightarrow \infty} 1$$

then for all $\varepsilon > 0$

$$\mathbb{P} \left(\sup_{t \in [0, T]} \|\mu_{N, Nt} - \Gamma_{u_0 + Nt + v_{N,t}}\|_{-r} \leq \varepsilon \right) \xrightarrow{N \rightarrow \infty} 1$$

where the random process converges weakly to $v_t = gt + a^2 w_t$, where w is a standard BM and a, b depend “explicitly” on the two first derivatives of Θ .

Step 1 : staying close to the manifold Γ

Proposition

Suppose that $\mathbb{P} \left(\|\mu_{N,0} - \Gamma_{u_0}\|_{-r} \leq \varepsilon \right) \xrightarrow{N \rightarrow \infty} 1$. Then

$$\mathbb{P} \left(\sup_{t \in [\log(N)/N, T]} \text{dist}(\mu_{N,t}, \Gamma) \leq N^{-(1/2-)} \right) \xrightarrow{N \rightarrow \infty} 1.$$

Key argument : mild formulation for the dynamics of

$\nu_{N,t} := \mu_{N,t} - \text{proj}_{\Gamma}(\mu_{N,t})$ on $[0, T]$:

$$\nu_{N,t} = \Phi_{t,0} \nu_{N,0} + \int_0^t \Phi_{t,s} R_s(\nu_{N,s}) ds + Z_{N,t},$$

- $\Phi_{t,s}$ is the semigroup of the linearized dynamics in a neighborhood of Γ , which has good contracting properties,
- $R(\nu)$ is quadratic in ν
- Z_N is a noise term of order $N^{-(1/2-)}.$

Step 2 : deriving the dynamics along the manifold Γ

Key argument : apply Ito formula to the the isochron map $\Theta(\mu_{N,t})$:

$$\begin{aligned}\Theta(\mu_{N,t}) = \Theta(\mu_{N,0}) + t - \frac{1}{N} \int_0^t D_1 \Theta_{\mu_{N,s}} \nabla \cdot (\sigma^2 \nabla p_{N,s}) \, ds \\ + \frac{1}{2} \int_0^t D^2 \Theta_{\mu_{N,s}} d \llbracket M_N \rrbracket_s + W_{N,t}.\end{aligned}$$

It remains to prove that the remaining terms in this formula give a nontrivial contribution on a time scale of order N .

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Merci de votre attention !