

Control and stabilization of PDEs

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Our PDEs today

Ω is a C^2 bounded open connected set in \mathbb{R}^N , ω is a non empty open subset of Ω

$$\begin{cases} \partial_t^2 u - \Delta u + 1|_{\omega} \partial_t u = 0 & \text{in } \Omega \times]0, +\infty[, \\ u = 0 & \text{on } \partial\Omega \times]0, +\infty[, \\ (u, \partial_t u)(\cdot, 0) = (u_0, u_1) \in H_0^1(\Omega) \times L^2(\Omega) . \end{cases}$$

Damped wave equation

$$\begin{cases} \partial_t a - d_1 \Delta a = 1|_{\omega} (b - a) & \text{in } \Omega \times]0, +\infty[, \\ \partial_t b - d_2 \Delta b = -1|_{\omega} (b - a) & \text{in } \Omega \times]0, +\infty[, \\ \partial_n a = \partial_n b = 0 & \text{on } \partial\Omega \times]0, +\infty[, \\ (a, b)(\cdot, 0) = (a_0, b_0) \in L^2(\Omega) \times L^2(\Omega) . \end{cases}$$

Reaction-diffusion coming out of reversible chemistry with $0 < d_1 < d_2$

Recall $u = u(x, t) = u(x_1, \dots, x_N, t)$ and

$$\Delta u = \partial_{x_1}^2 u + \dots + \partial_{x_N}^2 u = \frac{\partial^2}{\partial x_1^2} u + \dots + \frac{\partial^2}{\partial x_N^2} u \text{ and } \partial_n a = \nabla a \cdot n$$

Main results

Theorem 1. Under Geometrical Conditions

$$\|(u, \partial_t u)(\cdot, t)\|_{H_0^1 \times L^2(\Omega)} \leq C e^{-\beta t} \|(u, \partial_t u)(\cdot, 0)\|_{H_0^1 \times L^2(\Omega)}$$

Theorem 2. Suppose $|\Omega| = 1$ and $\int_{\Omega} a_0 + b_0 = 2$

$$\|(a - 1, b - 1)(\cdot, t)\|_{L^2 \times L^2(\Omega)} \leq C e^{-\beta t} \|(a_0 - 1, b_0 - 1)\|_{L^2 \times L^2(\Omega)}$$

Integration by parts

$$\int_{\Omega} \Delta u \partial_t u = - \int_{\Omega} \nabla u \partial_t \nabla u + \int_{\partial\Omega} \partial_n u \partial_t u = - \frac{1}{2} \frac{d}{dt} \int_{\Omega} |\nabla u|^2 ,$$

$$\int_{\Omega} \Delta a a = - \int_{\Omega} |\nabla a|^2 + \int_{\partial\Omega} \partial_n a a ,$$

$$\int_{\Omega} \Delta a = \int_{\partial\Omega} \partial_n a a ,$$

Poincare inequality

$$\int_{\Omega} \left| f - \frac{1}{|\Omega|} \int_{\Omega} f \right|^2 \leq C_P \int_{\Omega} |\nabla f|^2 .$$



$$E(t) = \int_{\Omega} |\nabla u(x, t)|^2 + |\partial_t u(x, t)|^2 dx := \|(u, \partial_t u)(\cdot, t)\|_{H_0^1 \times L^2(\Omega)}^2 .$$

Multiply $\partial_t^2 u - \Delta u + 1|_{\omega} \partial_t u = 0$ by $\partial_t u$ and integrate by parts

$$\frac{1}{2} \frac{d}{dt} E(t) + \int_{\omega} |\partial_t u(x, t)|^2 dx = 0 .$$

Integrate over Ω , $\partial_t a - d_1 \Delta a = 1|_{\omega} (b - a)$ and
 $\partial_t b - d_2 \Delta b = -1|_{\omega} (b - a)$

$$\frac{d}{dt} \int_{\Omega} a(x, t) + b(x, t) = 0$$

and multiply by (a, b) and integrate by parts

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int_{\Omega} |a(x, t)|^2 + |b(x, t)|^2 dx \\ & + \int_{\Omega} d_1 |\nabla a(x, t)|^2 + d_2 |\nabla b(x, t)|^2 dx + \int_{\omega} |(b - a)(x, t)|^2 dx = 0 . \end{aligned}$$

Control estimate and observation

Observability theorem . Under Geometrical Conditions

$$E(T) \leq K \int_0^T \int_{\omega} |\partial_t u(x, t)|^2 dx .$$

Observation at one point in time theorem . $\forall t \geq 1$

$$\int_{\Omega} |(a, b)(x, t)|^2 dx \leq C \left(\int_{\omega} |(a, b)(x, t)|^2 dx \right)^{\theta} \|(a_0, b_0)\|_{L^2 \times L^2(\Omega)}^{2(1-\theta)} .$$

Stabilization for the damped wave equation

From

$$\frac{1}{2} \frac{d}{dt} E(t) + \int_{\omega} |\partial_t u(x, t)|^2 dx = 0$$

and

$$E(T) \leq K \int_0^T \int_{\omega} |\partial_t u(x, t)|^2 dx$$

we have

$$E(T) \leq K \frac{1}{2} (E(0) - E(T))$$

which implies

$$E(T) \leq \frac{K/2}{1 + K/2} E(0) := \delta E(0) \text{ with } \delta \in]0, 1[.$$

Similarly for any integer $n \geq 0$

$$E((n+1)T) \leq \delta E(nT) \text{ with } \delta \in]0, 1[$$

and by induction

$$E(nT) \leq \delta^n E(0) \text{ with } \delta \in]0, 1[.$$

Let $t > 0$, there are $nT < t \leq (n+1)T$

$$E(t) \leq E(nT) \text{ and } \delta^n \leq e^{-|\ln \delta|(\frac{t}{T}-1)}$$

which implies

$$E(t) \leq ce^{-\beta t} E(0) .$$

Stabilization for reaction-diffusion system

Let $u_1 = a - 1$ and $u_2 = b - 1$. If $\int_{\Omega} a_0 + b_0 = 2$, then

$$\int_{\Omega} u_1(x, t) + u_2(x, t) = 0$$

and let

$$y(t) = \int_{\Omega} |u_1(x, t)|^2 + |u_2(x, t)|^2 dx := \|(a - 1, b - 1)(\cdot, t)\|_{L^2 \times L^2(\Omega)}^2.$$

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} y(t) + \int_{\Omega} d_1 |\nabla u_1(x, t)|^2 + d_2 |\nabla u_2(x, t)|^2 dx \\ + \int_{\omega} |(u_2 - u_1)(x, t)|^2 dx = 0 \end{aligned}$$

$$y(t) \leq C \left(\int_{\omega} |(u_1, u_2)(x, t)|^2 dx \right)^{\theta} (y(0))^{1-\theta} \text{ when } t \geq 1.$$

$$\begin{aligned}
 \int_{\omega} |(u_1, u_2)|^2 &\leq \int_{\omega} |u_1 + u_2|^2 + \int_{\omega} |u_1 - u_2|^2 \\
 &\leq \int_{\Omega} |u_1 + u_2|^2 + \int_{\omega} |u_2 - u_1|^2 \\
 &\leq C_P \int_{\Omega} |\nabla (u_1 + u_2)|^2 + \int_{\omega} |u_2 - u_1|^2 \\
 &\leq C \left(\int_{\Omega} d_1 |\nabla u_1|^2 + \int_{\Omega} d_2 |\nabla u_2|^2 + \int_{\omega} |u_2 - u_1|^2 \right) \\
 &\leq C \left(-\frac{1}{2} \frac{d}{dt} y(t) \right)
 \end{aligned}$$

$$\frac{y^{1/\theta}(t)}{C y^{1/\theta-1}(0)} \leq \int_{\omega} |(u_1, u_2)(x, t)|^2 dx \text{ when } t > 1$$

implies

$$\frac{d}{dt} y(t) + \frac{2}{C^2 y^{1/\theta-1}(0)} y^{1/\theta}(t) \leq 0.$$

Integrating over $[1, T]$ gives

$$y(T) \leq \delta y(0) \text{ with } \delta \in]0, 1[$$

and we conclude that

$$y(t) \leq ce^{-\beta t} y(0) .$$

Wave equation

Gaussian beams=solutions of the wave equation localized around curves: `movie1.mpg` and `movie2.mpg`

Babich (1968)

Ralston (1982)

Ziolkowski (1985)

Propagation of the microlocal regularity (Fourier analysis)

Hörmander (1970)

Melrose and Sjöstrand (1982)

Measure, defect measure

Lebeau (1996)

Microlocalization

Under Geometrical Conditions saying every ray meets $\omega \times]0, T[$

$$\begin{aligned}
 \|u\|_{L^2(\Omega \times]\delta, T-\delta])}^2 &\leq \sum_{finite} \int_{\mathbb{R}^{N+1}} |\Phi_i u|^2 dx dt \simeq \sum_{finite} \int_{\mathbb{R}^{N+1}} |\widehat{\Phi_i u}|^2 d\xi d\tau \\
 &\leq \sum_{finite} \sum_{finite} \int_{Conical\ set\ V_j} |\widehat{\Phi_i u}|^2 d\xi d\tau \\
 &\leq c \sum_{\rho=(\tilde{x}, \tilde{t}, \tilde{\xi}, \tilde{\tau})} \|u\|_{L^2_\rho}^2 + d \|u\|_{H^{-1}(\Omega \times]0, T])}^2 \\
 &\leq C \|u\|_{L^2(\omega \times]0, T])}^2 + d \|u\|_{H^{-1}(\Omega \times]0, T])}^2
 \end{aligned}$$

Heat equation

Heat kernel: $\frac{1}{t^{N/2}} e^{-|x-x_0|^2/4t}$

Logarithmic convexity of the energy

Agmon-Nirenberg (1963)

Cours de P.L.-Lions (2014): Équations paraboliques et ergodicité

Cours de L. Desvillettes (2017): Collisions in plasmas

Log convexity

$$\begin{cases} \partial_t u - \Delta u = 0 & \text{in } \Omega \times]0, +\infty[, \\ \partial_n u = 0 & \text{on } \partial\Omega \times]0, +\infty[. \end{cases}$$

$f : t \mapsto \int_{\Omega} |u(x, t)|^2 dx$ is a log convex function that is $\frac{d^2}{dt^2} \ln f(t) \geq 0$.

Indeed, $\frac{1}{2} \frac{d}{dt} \int_{\Omega} |u|^2 dx + \int_{\Omega} |\nabla u|^2 dx = 0$ that is $\frac{1}{2} \frac{d}{dt} \int_{\Omega} |u|^2 dx + \mathcal{N}(t) \int_{\Omega} |u|^2 dx = 0$

where $\mathcal{N}(t) = \frac{\int_{\Omega} |\nabla u|^2 dx}{\int_{\Omega} |u|^2 dx}$ is the frequency function.

$$\mathcal{N}'(t) = -\frac{1}{2} \frac{d}{dt} \ln f(t) .$$

But $\frac{1}{2} \frac{d}{dt} \int_{\Omega} |\nabla u|^2 dx + \int_{\Omega} |\Delta u|^2 dx = 0$ and $\mathcal{N}'(t) \|u\|^4 = -2 \|\Delta u\|^2 \|u\|^2 + 2 \|\nabla u\|^4 \leq 0$.

Log convexity

$$\begin{cases} \partial_t u - \Delta u = 0 & \text{in } \Omega \times]0, +\infty[, \\ \partial_n u = 0 & \text{on } \partial\Omega \times]0, +\infty[. \end{cases}$$

$f : t \mapsto \int_{\Omega} |u(x, t)|^2 dx$ is a log convex function that is $\frac{d^2}{dt^2} \ln f(t) \geq 0$.

$$\begin{aligned} \text{Therefore, } \ln f(\theta t_1 + (1 - \theta)t_2) &\leq \\ \theta \ln f(t_1) + (1 - \theta) \ln f(t_2) &= \ln f^\theta(t_1) f^{1-\theta}(t_2) \end{aligned}$$

$$\begin{aligned} \text{that is } \int_{\Omega} |u(x, \theta t_1 + (1 - \theta)t_2)|^2 dx &\leq \\ \left(\int_{\Omega} |u(x, t_1)|^2 dx \right)^\theta \left(\int_{\Omega} |u(x, t_2)|^2 dx \right)^{1-\theta} . \end{aligned}$$

Choose $t_1 = T$ and $t_2 = 0$ and $t = \theta t_1$,

$$\|u(\cdot, t)\|_{L^2(\Omega)} \leq \|u(\cdot, T)\|_{L^2(\Omega)}^{t/T} \|u(\cdot, 0)\|_{L^2(\Omega)}^{1-t/T} .$$

Log convexity and weight function

$$\begin{cases} \partial_t u - \Delta u = 0 & \text{in } \Omega \times]0, +\infty[, \\ \partial_n u = 0 & \text{on } \partial\Omega \times]0, +\infty[. \end{cases}$$

$f : t \mapsto \int_{\Omega} |u(x, t)|^2 e^{\Phi(x, t)} dx$ is it a log convex function ? we deform u to $ue^{\Phi/2}$.

Can we replace

$$\|u(\cdot, t)\|_{L^2(\Omega)} \leq \|u(\cdot, T)\|_{L^2(\Omega)}^{t/T} \|u(\cdot, 0)\|_{L^2(\Omega)}^{1-t/T}$$

by

$$\int_{\Omega} |u(x, t)|^2 e^{\Phi(x, t)} dx \leq C \left(\int_{\Omega} |u(x, T)|^2 e^{\Phi(x, T)} dx \right)^{\theta} \|u(\cdot, 0)\|_{L^2(\Omega)}^{2(1-\theta)}$$

in order to make appear $L^2(\omega)$. ok if $e^{\Phi/2}$ looks like the heat kernel

Comments and open problems

Ω is a C^2 bounded open connected set in \mathbb{R}^N , ω is a non empty open subset of Ω

$$\left\{ \begin{array}{l} \partial_t^2 u - \Delta u + k(x, t) 1_{|\omega} \partial_t u = 0 \quad \text{in } \Omega \times]0, +\infty[, \\ u = 0 \quad \text{on } \partial\Omega \times]0, +\infty[, \\ (u, \partial_t u)(\cdot, 0) = (u_0, u_1) \in H_0^1(\Omega) \times L^2(\Omega) . \end{array} \right.$$

Damped wave equation

$$\left\{ \begin{array}{l} \partial_t a - d_1 \Delta a = k(x, t) 1_{|\omega} (b - a) \quad \text{in } \Omega \times]0, +\infty[, \\ \partial_t b - d_2 \Delta b = -k(x, t) 1_{|\omega} (b - a) \quad \text{in } \Omega \times]0, +\infty[, \\ \partial_n a = \partial_n b = 0 \quad \text{on } \partial\Omega \times]0, +\infty[, \\ (a, b)(\cdot, 0) = (a_0, b_0) \in L^2(\Omega) \times L^2(\Omega) . \end{array} \right.$$

Reaction-diffusion coming out of reversible chemistry with

$$0 < d_1 < d_2$$

Thank You